

# On the recognition of $\frac{1}{2}$ -hyperbolic graphs: a subcubic equivalence with the $C_4$ -free graph recognition problem

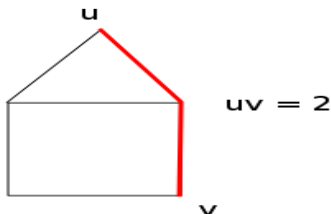
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# Understanding Graph Hyperbolicity

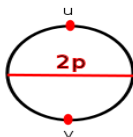
- graphs in this study are:
  - undirected;
  - simple;
  - **unweighted**;
  - and connected.



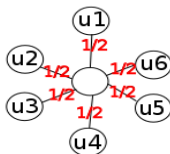
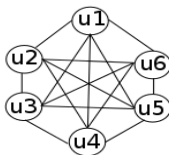
**distance** = length of a shortest-path  
(an edge = a path of length 1)

# A tree-like parameter

- which (maximum) gap between two  $u, v$ -shortest paths ?



- Tree: Unique shortest-path  $\rightarrow$  hyperbolicity 0
- Conversely:  
0-hyperbolic graph  $\rightarrow$  (weighted) tree metric



## Definition (4-points Condition, [Gromov, 1987])

Say that graph  $G$  is  $\delta$ -hyperbolic if, for every 4-tuple  $a, b, c, d$  of  $V$ , the two largest sums amongst

$$S_1 = d(a, b) + d(c, d),$$

$$S_2 = d(a, c) + d(b, d), \text{ and}$$

$$S_3 = d(a, d) + d(b, c)$$
 differ by at most  $2\delta$ .

The graph hyperbolicity, denoted  $\delta(G)$ , is the least  $\delta$  such that  $G$  is  $\delta$ -hyperbolic.

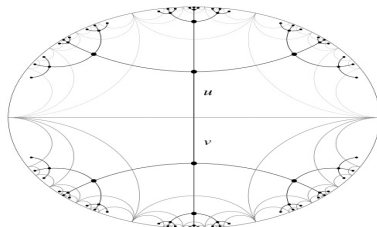
- Other "equivalent" definitions ( $\delta$ -slim triangles, Gromov product, ...).

# Some applications

- network security
- bioinformatics
- **routing**

→ **[Kleinberg, 2007]** embedding into a hyperbolic space

The resulting metric has to stay close to the metric of the graph.



## Can we compute the hyperbolicity value efficiently ?

State of the art:

- naive enumeration of 4-tuples ( $\Theta(n^4)$ );

**[Fournier et al., 2012]**

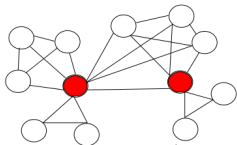
- reduction to (min, max) matrix product ( $O(n^{3.69})$ );

**[Coudert et al., 2012]**

- sorting of 2-tuples + breaking rule ( $O(n^4)$ ).

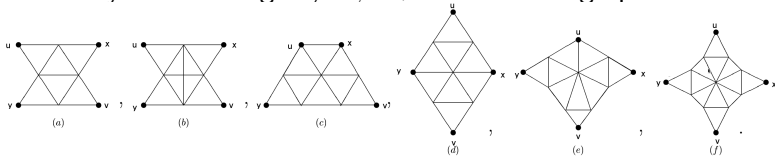
# Graphs with small hyperbolicity value

- Motivation: complex networks often have a bounded hyperbolicity value .
- **[Bandelt et Mulder, 1986]** 0-hyperbolic graphs: biconnected components = complete subgraphs  
→ linear-time recognition



- **[Bandelt et Chepoi, 2003]**  $\frac{1}{2}$ -hyperbolic graphs: *Forbidden* (isometric) subgraphs

- no cycle with length  $\neq 3, 5$  + six other subgraphs.



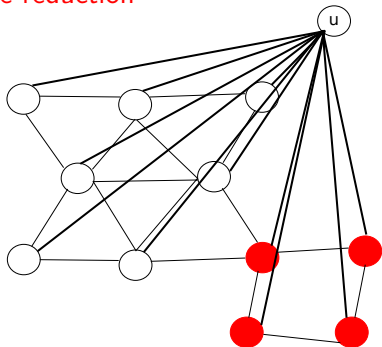
**The complexity of deciding if a graph is  $\frac{1}{2}$ -hyperbolic is equivalent to the complexity of finding an (induced)  $C_4$  in a graph.**

- both problems are reducible to fast rectangular matrix multiplication ( $O(n^{\omega(1,1,\log_n m)}) = O(n^{3.333953})$ ).



# $C_4$ -free detection $\propto \frac{1}{2}$ -hyperbolic recognition

- addition of a universal vertex  
→ linear-time reduction



(using **[Bandelt et Chepoi, 2003]**)  $C_4$  is the only forbidden subgraph in such case.

- Quickly excluding large (isometric) cycles:  
using a constant-factor approximation for hyperbolicity
  - $O(n^{2.69})$  [Fournier et al., 2012];
  - $\tilde{O}(n^{2.37})$  [Chalopin et al., 2013].

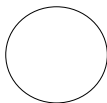
Given a  $c$ -factor approximation, denoted  $\delta_c(G)$ :

- If  $\delta_c(G) > \frac{c}{2}$ , then  $G$  is not  $\frac{1}{2}$ -hyperbolic;
- Otherwise,  $G$  does not contain isometric cycles with length  $\geq \Theta(c)$ .

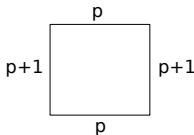
- Excluding the isometric cycles with length bounded by  $O(c)$ : using graph powers  $G = G^1, G^2, G^3, \dots, G^{O(c)}$ .

an edge in  $G^i$  = a path of length (at most)  $i$  in  $G$ .

→ computable in time  $\tilde{O}(n^{2.37})$



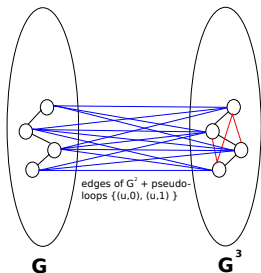
isometric  $C_{4p+2}$  in  $G$



induced  $C_4$  in  $G^{2p}$

- a simple computation shows that every  $G^i$  has to be  $C_4$ -free so that  $G$  is  $\frac{1}{2}$ -hyperbolic.

- Excluding the forbidden (isometric) subgraphs: using *modified* graph powers  $G^{[2]}, \dots, G^{[O(c)]}$ .



We use the characterization of **[Bandelt et Chepoi, 2003]** for the correctness.

- There is a linear-time reduction from the  $C_4$ -free graph recognition problem to the  $\frac{1}{2}$ -hyperbolic graph recognition problem.
  
- There is a **subcubic-time** reduction from the  $\frac{1}{2}$ -hyperbolic graph recognition problem to the  $C_4$ -free graph recognition problem.

# Finding an induced $C_4$

- Basic idea:  $G$  is  $C_4$ -free if, and only if, for every pair  $u, v \in V$  at a distance  $uv = 2$  we have  $N(u) \cap N(v)$  that is a clique.

This can be tested using two matrix multiplications:

- If  $A$  is the adjacency matrix of  $G$ , then  $A_{u,v}^2 = |N(u) \cap N(v)|$ ;
- If  $T$  is s.t.  $T_{u,e} = \delta_{e \in N(u)}$ , then
$$TT_{u,v}^\top = |\{e \in E : e \subseteq N(u) \cap N(v)\}|$$
;
- One has to check for every pair  $u, v \in V$  at a distance 2 that we have  $TT_{u,v}^\top = \frac{A_{u,v}^2(A_{u,v}^2 - 1)}{2}$ .

The time complexity is  $O(n^{\omega(1,1,\log_n m)})$   
(using [Huang et al., 1998]).

- Our results:
  - A subcubic equivalence between a *metric* problem (the recognition of a  $\frac{1}{2}$ -hyperbolic graph) and a *structural* problem (e.g. the detection of a  $C_4$ )
  - An improved algorithm in time  $O(n^{\omega(1,1,\log_n m)}) = O(n^{3.333953}) = o(n^{3.69})$
- Future work: extending our results to 1-hyperbolic graphs  
→ this would yield a 4-factor approximation for the hyperbolicity

- **[Bandelt et Chepoi, 2003]**  
Bandelt, H. J., Chepoi, V. (2003). 1-Hyperbolic graphs. *SIAM Journal on Discrete Mathematics*, 16(2), 323-334.
- **[Bandelt et Mulder, 1986]**  
Bandelt, H. J., Mulder, H. M. (1986). Distance-hereditary graphs. *Journal of Combinatorial Theory, Series B*, 41(2), 182-208.
- **[Chalopin et al., 2013]**  
Chalopin, J., Chepoi, V., Papasoglu, P., Pecatte, T. (2013). Cop and robber game and hyperbolicity. *arXiv preprint arXiv:1308.3987*.
- **[Coudert et al., 2012]**  
Cohen, N., Coudert, D., Lancin, A. (2012). Exact and approximate algorithms for computing the hyperbolicity of large-scale graphs.



- **[Fournier et al., 2012]**  
Fournier, H., Ismail, A., Vigneron, A. (2012). Computing the Gromov hyperbolicity of a discrete metric space. *arXiv preprint* arXiv:1210.3323.
- **[Gromov, 1987]**  
Gromov, M. (1987). Hyperbolic groups (pp. 75-263). Springer New York.
- **[Huang et al., 1998]**  
Huang, X., Pan, V. Y. (1998). Fast rectangular matrix multiplication and applications. *Journal of complexity*, 14(2), 257-299.
- **[Kleinberg, 2007]**  
Kleinberg, R. (2007, May). Geographic routing using hyperbolic space. In *INFOCOM 2007. 26th IEEE International Conference on Computer Communications*. IEEE (pp. 1902-1909). IEEE.

